

Safety Manual for SIS

XMT1000 SIL

Ultrasonic Liquid Flowmeter



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Please visit <https://panametrics.com/services> for more details.

Typographical Conventions

Note: These paragraphs provide information that provides a deeper understanding of the situation, but is not essential to the proper completion of the instructions.

IMPORTANT: These paragraphs provide information that emphasizes instructions that are essential to proper setup of the equipment. Failure to follow these instructions carefully may cause unreliable performance.



CAUTION! This symbol indicates a risk of minor personal injury and/or damage to the equipment unless these instructions are followed carefully.



WARNING! This symbol indicates a risk of serious personal injury unless these instructions are followed carefully.

Safety Issues



WARNING! It is the responsibility of the user to follow all site rules and applicable regulatory requirements.



IMPORTANT Any instructions on grounding and cable termination in this manual are necessary for compliance with global EMC / RFI standards. Such compliance may be required by National EMC / RFI legislation.

Local Safety Standards

The user shall ensure that he operates the equipment in accordance with the applicable local codes, standards, regulations, or laws.

Qualification of Personnel

Ensure that all personnel have applicable training to use the equipment.

Personal Safety Equipment

Ensure that operators and maintenance personnel have all safety equipment applicable.

Unauthorized Operation

Ensure that unauthorized personnel cannot gain access to the operation of the equipment.

Environmental Compliance

Waste Electrical and Electronic Equipment

This apparatus required the extraction and use of natural resources for its production. It may contain hazardous substances that could impact health and the environment. To avoid the dispersal of these substances into our environment and to reduce the pressure on natural resources, we encourage you to use an appropriate “take-back” resource recovery scheme. These schemes will reuse or recycle most of the materials of your end-of-life equipment in an environmentally responsible way. The crossed-out wheeled bin symbol marked on the product invites you to use such a scheme.



If you need more information on the collection, reuse and recycling systems, please contact your local waste management administration.

As part of its commitment to the environment and the EU's WEEE Directive 2012/19/EU, Panametrics participates in a take-back scheme.

Please visit <https://panametrics.com/health-safety-and-environment-hse> for take-back instructions and more information about this initiative.

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Chapter 1. Introduction

1.1 Purpose

The purpose of the Safety Manual is to define the Functional Safety aspects of the XMT1000-SIL Ultrasonic Flowmeter.

IMPORTANT: This version of the Safety Manual is compatible with hardware revisions 703-1918 revision A and 703-2004 revision B.

1.2 Terms and Abbreviations

Safety – Freedom from unacceptable risk of harm.

Functional Safety – The ability of a system to carry out the actions necessary to achieve or to maintain a defined safe state for the equipment / machinery / plant / apparatus under control of the system.

Basic Safety – The equipment must be designed and manufactured such that it protects against risk of damage to persons by electrical shock and other hazards and against the risk of creating fire and explosion. The protection must be effective under all conditions of the nominal operation and under single fault condition.

Safety Assessment – The investigation to arrive at a judgment – based on evidence – of the safety achieved by safety-related systems.

Note: Further definitions of terms used for safety techniques and measures and the description of safety related systems are given in IEC 61508-4.

E/E/PE – the electrical and/or electronic and/or programmable electronic elements of an SIF. In short, these elements are the Functional Safety electronics.

FMEDA – Failure Modes, Effects and Diagnostic Analysis

HART – Highway Addressable Remote Transducer

PFD_{avg} – Average Probability of Failure on Demand

SIF – a specific single set of actions and the corresponding equipment needed to identify a single hazard and act to return a system to a safe state. A Safety Instrumented System (SIS) is comprised of several individual SIF's.

SIL – Safety Integrity Level, discrete level (one out of a possible four) for specifying the safety integrity requirements of the safety functions to be allocated to the E/E/PE safety-related systems where Safety Integrity Level 4 has the highest level of safety integrity and Safety Integrity Level 1 has the lowest.

SIS – Safety Instrumented System – Implementation of one or more Safety Instrumented Functions. A SIS is composed of any combination of sensor(s), logic solver(s), and final element(s).

1.3 Intended Audience and Reading Suggestions

This manual is intended for the Safety Engineer at the customer site. The manual will also provide a useful reference for other stakeholders working with the flowmeter.

For users who are unfamiliar with Functional Safety terminology and concepts, we recommend starting with the Glossary at the end of this manual. Once familiar with Functional Safety concepts, the user may want to refer to the section of the manual that is appropriate for the life cycle phase of the Flowmeter. The main sections are Installation and Commissioning, Maintenance, and Decommissioning.

1.4 Scope

This manual covers the following aspects of Functional Safety for the XMT1000-SIL:

- Functional Safety Specifications of XMT1000-SIL
- Installation and commissioning
- Maintenance, proof testing, service, and repair
- Decommissioning
- Contact information

1.5 References

The following documents are referenced in this manual:

- Functional Safety Standard IEC-61508.
- User Manual, available on the Panametrics Literature Library web site: <https://panametrics.com>
- FMEDA, XMT1000 SIL Ultrasonic Flowmeter; Report No. PAN 20-04-115 R001, V5, R2, exida FMEDA 80 N. Main St, Sellersville, PA 18960.

1.6 XMT1000-SIL Functional Safety Characteristics

The PanaFlow flow meters consist of a set of ultrasonic sensors (transducers) and XMT1000 electronics that drive the transducers, calculate the flow rate, and transmit this flow rate to the Safety Instrumented System (SIS) over the SIL Output. There are several types of ultrasonic sensor assemblies, which go by several model names: PanaFlow HT, PanaFlow Z3, PanaFlow LZ, and PanaFlow LC. Each of these models has specific transducer options and path configurations, but all the models have a common safety chain: ultrasonic sensor is connected to measurement unit through a cable assembly, and the measurement unit connects to the customer system through the output circuit, as shown in *Figure 1*. The probability of failure for this assembly is listed in *Table 1*.

Per the exida FMEDA report:

"According to IEC 61508-2 the architectural constraints of an element must be determined. This can be done by following the 1H approach according to 7.4.4.2 of IEC 61508-2 or the 2H approach according to 7.4.4.3 of IEC 61508-2, or the approach according to IEC 61511:2016 which is based on 2H (see Section 5.2 of the *exida FMEDA* report.)

The 1H approach involves calculating the Safe Failure Fraction for the entire element.

The 2H approach involves assessment of the reliability data for the entire element according to 7.4.4.3.3 of IEC 61508-2.

The failure rate data used for this analysis meet the *exida FMEDA* criteria for Route 2H (see Section 5.2 of the *exida FMEDA* report) and the diagnostic coverage resulting from the analysis exceeds the required 60% threshold. Therefore, the XMT1000 SIL meets the hardware architectural constraints for up to SIL 2 at HFT=0 (or SIL3 @ HFT=1) when the listed failure rates are used."

See *Table 1* below for the listed failure rates.

Table 1: Failure Rates with Good Maintenance Assumptions in FIT @ SSI=2

Failure Category	Failure Rate (FIT)	
Fail Safe Undetected	1089	
Fail Dangerous Detected	5487	
Fail Detected (detected by internal diagnostics)	5161	
Fail High (detected by logic solver)	7	
Fail Low (detected by logic solver)	319	
Fail Dangerous Undetected	650	
No Effect	2774	
Annunciation Undetected	31	

The SIL Output is through the analog input/output terminal block (TB2) per drawing 702-2040.

From a Functional Safety perspective, the PanaFlow consists of three parts:

- The sensor and cable harness assembly
- The measurement unit, which includes the flow measurement circuitry
- The output circuit, which drives the 4-20 mA signal

The error distribution for Functional Safety is broken down as shown in *Table 1*.

Table 1 above lists the *Functional Safety Characteristics* for the components of the PanaFlow system. The table shows a breakdown of the risk allowance for the measurement system.

The safety chain of the PanaFlow consists of four components: the ultrasonic sensor (US-Sensor), the cable harness assembly, the measurement unit (a circuit inside the electronics enclosure), and the output circuit (another circuit inside the electronics).

Figure 1 on *page 3* identifies the physical location of the PanaFlow safety chain components.

1.6.1 System Description

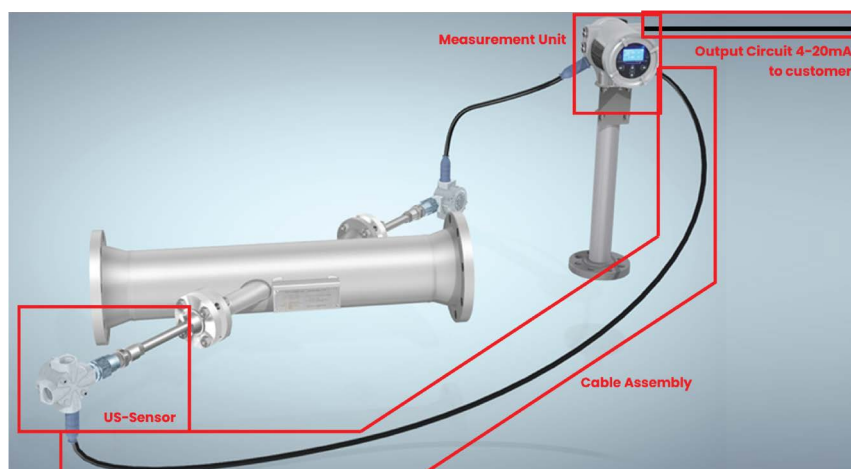


Figure 1: Functional Safety Chain

1.6.2 Safety Function

The Safety Function for the PanaFlow is volumetric or mass flow rate. An *Authorized User* can select which function to use. See Chapter 3, Installation and Commissioning, for details and Chapter 3 of the *XMT1000 User's Manual* for programming instructions.

When measuring properly, the SIL output (pins 1 and 2 on analog input/output terminal -TB2) will be kept in 4-20 mA range to indicate to the SIS that there is a valid measurement.

A Functional Safety failure is indicated if the instrument could calculate an incorrect flow rate due to flow measurement errors or system faults. The instrument will react to a failure by setting the SIL Output (Pins 1 and 2 on TB2) to the Dangerous Detected state and setting an error message on the front screen and in the Modbus health register. These actions will alert the SIS that the instrument may not make a reliable flow measurement. The instrument will take these actions within one minute of detecting a failure. To clear the Dangerous Detected state, see *Section 4.1* on *page 25* for instructions.

An Authorized User can configure the Dangerous Detected output current (SIL Output - Pins 1 and 2 on TB2) as either Fire Low (3.6 mA) or Fire High (21.0 mA). See *Section 3.2.3* on *page 13* and *Chapter 3* of the *User Manual* for programming instructions.

The safety function is guaranteed when the electronics operates within the specified environmental limits. See *Section 1.6.3* on *page 4* for functional safety characteristics of the instrument.

1.6.3 Functional Safety Characteristics

The Functional Safety Related characteristics of the PanaFlow are as follows:

Table 2: Design Criteria

SIL Safety Integrity Level	2	Useful Lifetime	10 years
HFT Hardware Fault Tolerance	0	Proof test Interval	1 year
Type of safety related elements	Type B	MTTR Mean time to Recovery	24 h
Demand mode	Low	Safety function reaction time	1 min

Table 3: Failure Rates for Static Applications with Good Maintenance Assumptions in FIT@ SSI=2 according to IEC 61508

Application/Device/Configuration	λ_{SD}	λ_{SU}^3	λ_{DD}	λ_{DU}	#	DC
XMT 1000 SIL	0	1089	5487	650	2805	89%
Mechanical Clamp	0	0	0	21	11	0%

Where:

λ_{SD} = Fail Safe Detected

λ_{SU} = Fail Safe Undetected

λ_{DD} = Fail Dangerous Detected

λ_{DU} = Fail Dangerous Undetected

= No Effects Failures

These failure rates are valid for the useful lifetime of the product, see Appendix A of the *exida FMEDA* report (See "References" on page 2.).

According to IEC 61508-2 the architectural constraints of an element must be determined. This can be done by following the 1_H approach according to 7.4.4.2 of IEC 61508-2 or the 2_H approach according to 7.4.4.3 of IEC 61508-2, or the approach according to IEC 61511:2016 which is based on 2_H (see Section 5.2 of the *exida FMEDA* report).

The 1_H approach involves calculating the Safe Failure Fraction for the entire element.

The 2_H approach involves assessment of the reliability data for the entire element according to 7.4.4.3.3 of IEC 61508-2.

The failure rate data used for this analysis meets the *exida FMEDA* criteria for Route (see Section 5.2 of the *exida FMEDA* report) (and the diagnostic coverage resulting from the analysis exceeds the required 60% threshold). Therefore, the XMT1000 SIL is B. The hardware fault tolerance of the device is 0. The SIS designer is responsible for meeting other requirements of applicable standards for any given SIL.

Table 3 lists the failure rates for the XMT1000 SIL according to IEC 61508 with a Site Safety Index (SSI) of 4 (perfect site maintenance practices). This data should not be used for SIL verification and is provided only for comparison with other analysis than has assumed perfect maintenance. See Appendix E of the *exida FMEDA* report for an explanation of SSI.

Note: The Mean Time to Recovery design criteria of 24 hours depends on the customer purchasing a spare set of electronics, sensors, and cables or a special service plan to ensure we can replace a defective system within 24 hours. If the customer chooses a different Mean Time to Recovery strategy, the System Characteristics will have to be recalculated by the Safety Engineer at the customer site.

Assumptions:

The analysis above was conducted under certain assumptions, documented in the *exida FMEDA* report. The user is responsible for ensuring these assumptions are valid: 1. The application program in the logic solver is constructed in such a way that Fail High and Fail Low failures are detected regardless of the effect, safe or dangerous, on the safety function; 2. Materials are compatible with process conditions; 3. The device is installed and operated per manufacturer's instructions; and 4. External power supply failure rates are not included in the product failure rates.

1.6.4 Safety Integrity Parameter Settings

Certain programmable parameters need to be set prior to operation to maintain the designed safety integrity: These parameters are described in Section 3.2.3.

1.6.5 Functional Safety Specifications

Please note that the PanaFlow was designed to meet the following *Functional Safety* specifications:

- Safety Accuracy – The PanaFlow has a measurement accuracy error limit that ranges from $\pm 0.25\%$ to $\pm 1.0\%$ of the flow measurement typically. The safety accuracy of the system is 4x the measurement accuracy limit, ranging from $\pm 1\%$ to $\pm 4\%$. This means that if the instrument detects an error condition that could lead to an inaccuracy greater than the safety accuracy limit, the SIL output will go to the Dangerous Detected state.
- Diagnostic Response Time – The instrument shall respond to a fault condition within 60 seconds.
- Startup Time – The instrument shall start making measurements within 10 minutes of applying power.
- Reliability Data and Lifetime Limit – The instrument is designed for a 10-year lifetime.
- Environmental Limits for the electronics:
 - Storage Temperature -55° to $+75^{\circ}\text{C}$
 - Ambient Temperature Range: -40°C to $+60^{\circ}\text{C}$
 - Relative Humidity from 10% to 90% (non-condensing)
 - Vibration tested to 2041 kgf for sine and random (5 Hz, 100 Hz, and 200 Hz)
 - Shock tested to 4042 kgf from 5 Hz to 500 Hz
- Application Limits – Valid fluid temperature range varies by meter type, with the widest range being -200°C to 600°C . In all cases, the fluid type includes any acoustically conductive fluids.

1.6.6 Prevention from Unauthorized Modification

During installation and commissioning, unauthorized personnel shall not be able to modify some parts of the system. These modifications could possibly result in a dangerous fault of the system. For this reason, a User password is required to access these parameters. This password shall be safeguarded against unwarranted dissemination.

1.7 Product Safety Officer

Any failures that are detected and that compromise functional safety should be reported to the Product Safety Officer within Panametrics. Please contact Panametrics Customer Service or Panametrics Technical Support. Contact information is provided on the back cover of this manual.

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Chapter 2. Communication Tools

2.1 Measurement and Configuration

Measurement data can be collected from the XMT1000-SIL, and Configuration data can be programmed into the XMT1000-SIL, using the following communication tools:

- PanaView Plus PC Software from Panametrics
- The LCD/Keypad on the transmitter
- A HART or Fieldbus Configurator.
- A Foundation Fieldbus Device

2.2 Proof Testing

The proof test instructions in this manual are designed for use with PanaView Plus PC software or the LCD/Keypad on the flowmeter, using the latest firmware revision.

Refer to the *User's Manual* for information on connecting the PanaView Plus PC Software to the flowmeter.

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Chapter 3. Installation and Commissioning

Before using the flowmeter as part of an SIS, the XMT1000-SIL must be installed and provided with initial programming. These Installation and Commissioning activities must be performed by trained Service personnel, or by an Authorized User who has received installation and commissioning training from Panametrics.

3.1 Introduction

Installation refers to the physical installation of the XMT1000-SIL into a pipeline, and physical connection to the SIS. Commissioning is accomplished in three steps:

- Adjustment of programmable parameters to match the specific conditions of the application
- Storage of that data set to the Commissioned Data Set for later retrieval as needed
- Storage of data for traceability

After the Commissioned Data Set has been established, the operator will save the same data set as the Active Data set, which is used by the Flowmeter to make measurements. Any changes to programmed values after the date of commissioning will be made to the Active Data Set, leaving the Commissioned Data Set unchanged. If at any point there is an error in the Active Data Set, the Authorized User may revert the Active Data Set to the Commissioned Data Set, which will put the Flowmeter into a known working condition. Similarly, the Service Person may overwrite the Commissioned Data Set with the Factory Data Set if there is an issue during Commissioning. Since the integrity of the SIL Output is so critical, the Flowmeter maintains all three data sets in memory as a backup, in case of error.



WARNING! Customers should only connect a host computer to the XMT1000-SIL with a direct wired connection. Use of any USB to TCP/IP conversion software or devices to connect through Internet is NOT recommended.

3.1.1 Role of the Authorized User

The Authorized User is responsible for protecting the safety of the SIS parts that are outside the scope of the XMT1000 SIL system (PanaFlow HT, PanaFlow LZ, PanaFlow Z3, and PanaFlow LC). The Authorized User shall be allowed to take the XMT1000-SIL out of the DD state, and it shall be his responsibility to prevent the SIS from misinterpreting that reading. Panametrics shall ensure the instrument acts in a predictable, controlled way. To clear the Dangerous Detected state, see *Section 4.1 on page 25* for instructions.



IMPORTANT: Security Advisory

It is the full responsibility of the end user to observe the cyber security precautions for this product. The authorized user must maintain and safeguard the user level passwords that are required to access program parameters in the instrument via the keypad, PanaView Plus software, HART or Modbus. The user must safeguard program site files that are maintained outside the instrument and loaded via digital communications. The user must connect to the instrument via a direct wired connection. Any connection to the Internet is not recommended.

3.1.2 Use in Safety Instrumented System

The flowmeter is designed to make flow measurement as an input to a larger Safety Instrumented System (SIS).

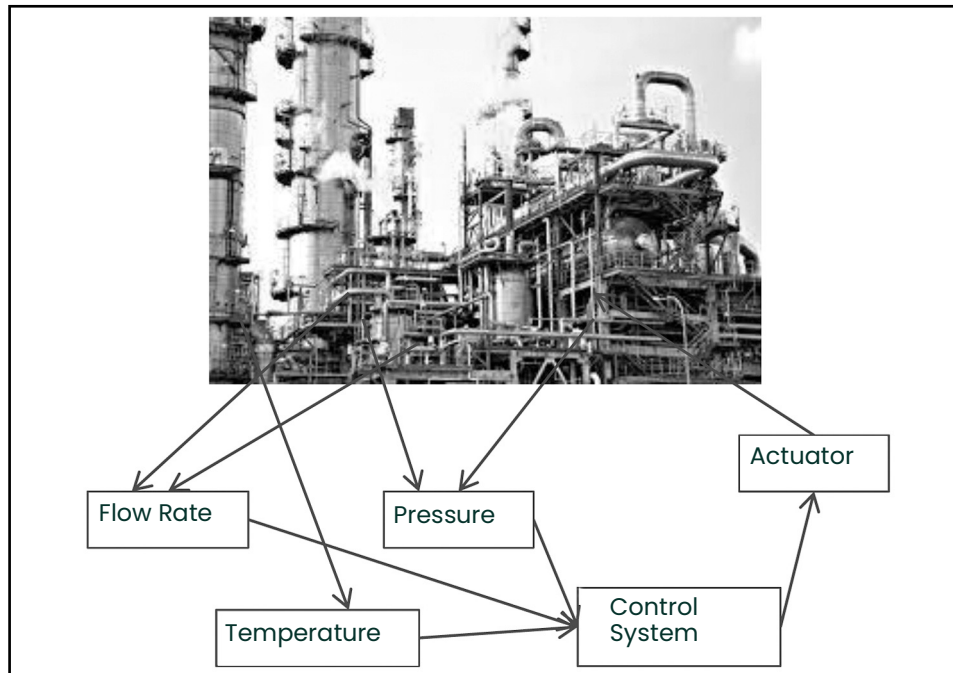


Figure 2: Components of a Safety Instrumented System (SIS)

The system maintains a safe state by monitoring various conditions and using actuators to keep the process safe. The goal of the SIS is not efficiency or productivity, but purely the avoidance of a hazard.

A single XMT1000-SIL is designed to SIL-2 safety level, but two redundant systems can be used together to achieve a SIL-3 measurement, if used on the same flow measurement point.

The SIL-2 and SIL-3 safety level for this product was determined by design, not simply by proven-in-use records. Please note that failure rates of external power supplies and other external components are not included in the calculations of failure rates.

3.1.2 Use in Safety Instrumented System (cont.)

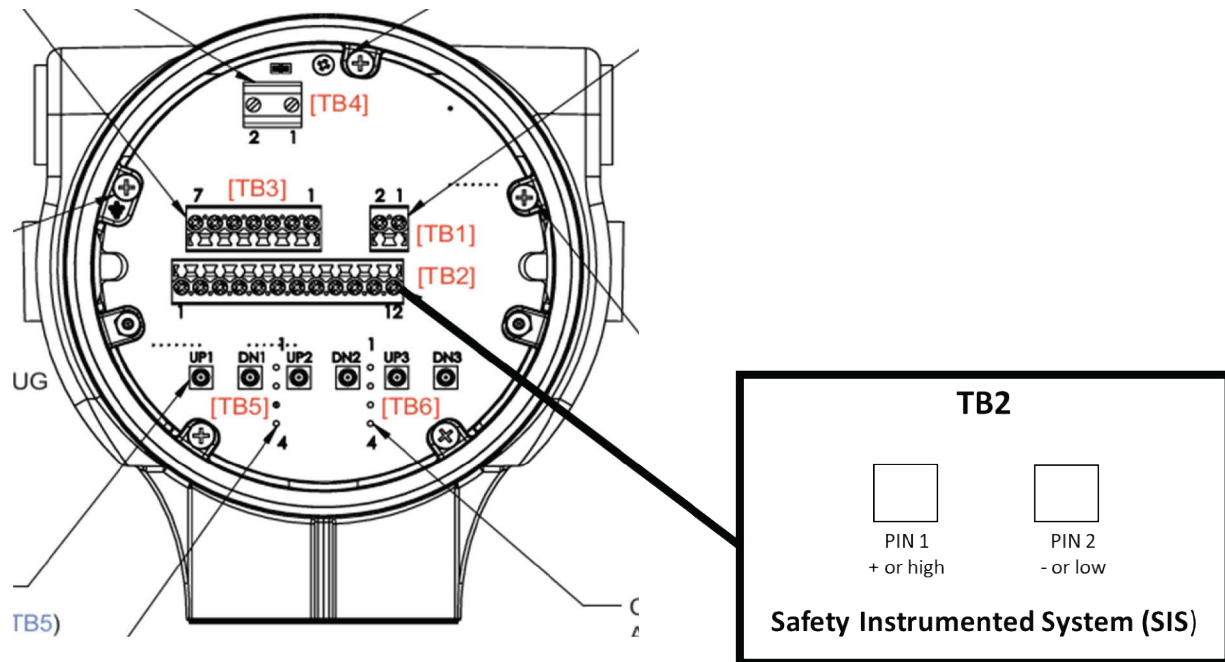


Figure 3: SIL Analog Output

This single SIL analog output is to be used as an input to a customer SIS, providing a functional safety flow measurement to the overall safety system. This measurement may be combined with other measurement inputs by the Authorized User at the SIS level. It is the Authorized User's responsibility to address issues of bringing non-safety variables into a safety configuration where variables are not fully covered by a SIL certified safety path. The XMT1000 SIL through the PanaFlow HT, PanaFlow LZ, PanaFlow Z3 or PanaFlow LC is not responsible for the integrity of the SIS beyond the flow measurement it provides.

The XMT1000-SIL provides several input/output connections. Only the SIL Analog Output is SIL rated and may be used as an input to the SIS.

3.1.3 Operating Modes: Measurement (Safe) and Configuration (Non-Safe)

The XMT1000-SIL has two operating modes. The default mode is Measurement, during which the measurement unit inside the XMT1000-SIL electronics will make flow measurements based on an ultrasonic interrogation of the fluid in the spoolpiece. The second mode, Configuration, is intended only for changing programmed parameters, and is a temporary condition.

Measurement Mode is the safe operating mode. In this mode, the XMT1000-SIL will make flow measurements and drive a SIL Output value. If the flow calculation passes all internal tests and has been verified for accuracy, the SIL output will reflect the flow measurement. If the XMT1000-SIL detects a chance that the flow measurement might not be accurate, the SIL output will go to the Dangerous Detected state so the SIS does not use the potentially erroneous flow measurement value. The instrument will remain in the Dangerous Detected state until an Authorized User intervenes.

Configuration Mode is unsafe because the calculation is dependent on these settings, and changing the parameters can lead to inaccurate flow measurement. An Authorized User can put the instrument into Configuration Mode by entering the program menu with a password. When entering this mode, the SIL Output will go to the Dangerous Detected state as a precaution. A change in programmed parameters could affect the accuracy of the SIL Output, so the output goes to the Dangerous Detected state, notifying the SIS that it is not providing a Functionally Safe flow measurement. The error line on the LCD will indicate S1 Config Mode.



WARNING! The SIL Analog Output measurement will shift to the Dangerous Detected state when the instrument goes into Program mode. Please notify the control room before entering programming mode.

3.2 Safety Integrity Parameter Settings

The configuration process must ensure data validity and integrity of the safety parameters. This section details the configuration process and user requirements for configuring the flowmeter to meet Functional Safety requirements.

Note: Please follow the instructions in the User Manual carefully when changing parameters that require a SIL User password. Entry of incorrect parameters can result in measurement problems.

Safety Parameters are composed of nearly every item in the Data Set. Therefore, some of the parameters have been set by Factory personnel and are not accessible to the Authorized User. Another group of parameters are accessible only by a Admin password, and are generally changed only during Commissioning. The final set of Safety Parameters are accessible to the Authorized User via the SIL User password, but must be changed only with great care.

Changing parameters requires the Authorized User to put the flowmeter into Configuration mode. This will cause the SIL Output to go to the DD state. Therefore, changes to parameters can happen after the Authorized User has disconnected the flowmeter from the SIS.

Also note that the Authorized User is allowed to set the SIL output to any value between 0 and 22 mA during Configuration, in order to calibrate the SIL output to the DCS. This is another reason why the Authorized User must set the SIS to ignore this SIL output prior to entering Configuration mode.

3.2.1 Configuring with Display/Keypad or HART

When using the Display/Keypad or HART/FF communications, each parameter is changed by this sequence:

1. Communications interface displays the currently programmed value.
2. Authorized User changes the value.
3. Communications interface reads the value from memory and displays the "as programmed" value.
4. Authorized User accepts or rejects the value that is in memory. To accept the value, simply move on to the next parameter. To reject the change, return to step 2 and change the parameter again.
5. After making all parameter changes, the Authorized User will exit Configuration Mode. At this step, the Authorized User can select Save and Logout or Cancel.

3.2.2 Configuring with PanaView Plus PC Software

When the PanaView Plus Software is used to configure parameters, the process is slightly different.

1. Ensure that while using PanaView Plus software for programming, flowmeter is not in measurement mode.
2. PanaView Plus software displays all currently programmed values in configuration section.
3. Authorized user can set a new value of configuration parameter. When value is successfully written, background of parameter changes to yellow.
4. After pressing save button, PanaView Plus displays all changed values in the session. In this step, user can see all the changed values at once and verify them before saving the data set

3.2.3 List of Safety Parameters

The following tables indicate what parameters need to be set in order to maintain the designed safety integrity. The tables also list the reason for each parameter. The category indicates who may set the parameters (Access Level) and under what conditions.

- **Category 1:** Set by Authorized User prior to operation.
- **Category 2:** Set by Authorized User if desired measurement is standardized volumetric
- **Category 3:** Factory setting but may be changed by Authorized User
- **Category 4:** Factory settings that can be changed by Qualified Service Personnel
- **Category 5:** Factory setting but may be changed by Panametrics Service Engineer
- **Category 6:** Factory setting during calibration and should not be changed
- **Category 7:** Factory setting that should not be changed.

Category 1 – Wetted Transducers: Must be set by Authorized User prior to operation as part of a SIL system

Unit Type Volumetric	Needed only if the user wishes to use a Volumetric unit type different from m ³ /sec, the default unit type.
SIL Output Selection (SIL and HART output)	Default is Actual Volumetric Flow. If this is not the desired SIL measurement, it can be set to Mass Flow. To specify if the mA output should represent Actual Volumetric Flow or Mass Flow.
High Set point as entered in the system	Determines the flow measurement that corresponds to 20 mA on the SIL output. Affects the scaling of the 4-20 mA value.
Low Set point as entered in the system	Determines the flow measurement that corresponds to 4 mA on the SIL output. Affects the scaling of the 4-20 mA value.
Selection for Fire Low / Fire High during fault	To specify if the mA output should go high (>22 mA) or low (<3.6 mA) upon detection of an internal failure.
Static Density	Required only if Standard Volumetric Flow or Mass Flow will be measured. Mass Flow is equal to Volumetric Flow multiplied by Density.
Kinematic Viscosity	Needed only if Composite Reynolds Correction is set to "On". The instrument uses this value to determine the fluid Reynolds Number.

Category 1 – Clamp-On Transducers: Must be set by Authorized User prior to operation as part of a SIL system

Pipe Outer Diameter (OD)	Required only if the Pipe Inner Diameter is not set directly. In this case the Pipe Inner Diameter will be calculated from the Pipe Outer Diameter and Pipe Wall Thickness.
Pipe Wall Thickness or Pipe ID	Required only if the Pipe Inner Diameter is not set directly. In this case the Pipe Inner Diameter will be calculated from the Pipe Outer Diameter and Pipe Wall Thickness.
Pipe Material	For Clamp-on installations, the path of the ultrasonic signal is determined partly by the sound speed of the pipe material. The user must select a pipe material for the software to determine where to place the receiving transducer, or if the specific pipe material is not listed, select Other.

Category 1 – Clamp-On Transducers: Must be set by Authorized User prior to operation as part of a SIL system

Pipe Sound Speed if Material = Other	If the pipe material is set to "Other," the user must indicate the pipe material sound speed. Be sure to enter the correct pipe sound speed for your specific pipe material.
Lining Material	If the pipe has a lining, the path of the ultrasonic signal is determined partly by the sound speed of the pipe lining. The user must select a pipe lining material for the software to determine where to place the receiving transducer, or if the specific pipe lining material is not listed, select Other.
Lining Sound Speed if Material = Other	If the pipe lining material is set to "Other," the user must indicate the sound speed of the unknown pipe lining. Be sure to enter the correct sound speed for your specific pipe lining material.
Lining Thickness	For Clamp-on installations, the path of the ultrasonic signal is partly determined by the thickness of the pipe lining. Be sure to enter an accurate thickness or the ultrasonic signal may miss the receiving transducer.
Fluid Type	For Clamp-on installations, the path of the ultrasonic signal is determined partly by the sound speed of the fluid in the pipe. The user must select a fluid type for the software to determine where to place the receiving transducer, or if the specific fluid type is not listed, select Other.
Fluid Nominal Soundspeed if Type = Other	If the fluid type is set to "Other," the user must indicate the nominal fluid sound speed. Be sure to enter the correct fluid sound speed for your specific installation.
Path Configuration	Defines the number of transducer pairs mounted on the flow cell and the arrangement of those paths. This information is critical to determining the flow measurements to create an overall flow rate measurement algorithm, as it defines how to combine the individual path.
Path Weights (Ch_x Chord Wt factor)	Required if the Composite Path Configuration is more than one path. Defines the weighting factor when calculating the overall volumetric flow rate from the flow rate of each transducer path. This is used in the flow rate calculation.

If Transducer = Special*

Transducer Frequency*	Select the transmit frequency of the ultrasonic transducer. This defines the signal processing algorithm, so an accurate measurement depends on this being correct.
Static Tw*	Tw is a parameter of the transducer that affects the accuracy of the transit time and sound speed measurements. This value should only be changed by the factory or authorized service personnel.
Wedge Angle*	Transducer Wedge Angle is a parameter of the transducer that partly determines the path of the ultrasonic signal. This can have a direct impact on measurement accuracy. This value should only be changed by the factory or authorized service personnel.
Wedge Soundspeed*	Transducer Wedge Soundspeed is a parameter of the transducer that partly determines the path of the ultrasonic signal. This can have a direct impact on measurement accuracy. This value should only be changed by the factory or authorized service personnel.
No. of Traverses*	For clamp-on transducers, number of traverses indicates how many times the ultrasonic signal will traverse the fluid before it reaches the receiving transducer. This setting optimizes the intensity of the received signal with the amount of fluid interrogated by the signal, and is highly dependent on the specific application. This setting directly affects measurement accuracy and reliability, and should only be determined by qualified service personnel.
Spacing*	The recommended spacing of the clamp-on transducers will be calculated by meter software and presented to the user, but mechanical coupling to the pipe has accuracy limitations. Therefore, the user must enter the "as installed" actual spacing of the transducers to ensure measurement accuracy and reliability. This value should be measured and entered only by qualified service personnel.

Category 2: Must be set by Authorized User if the Unit Type Volumetric is Standard Volumetric Flow or if Mass Flow is used.

Reference Density for Standard volumetric calculation	Needed only for Standard Volumetric Flow measurement. Standard Volumetric Flow is equal to Actual Volumetric Flow multiplied by the ratio of the Actual Density to the Reference Density.
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Category 3: Set at Factory, but may be changed by Authorized User for difficult applications

Response Time	Defines how heavily damped the final flow measurement is. A long response time provides a smooth output value but a slower response to sudden changes in the flow rate. A short response time is more accurate for sudden flow changes, but very jittery at the output.
Zero Cutoff	Not critical. Near zero flow, measurement error is significant. Results in an extremely variable measurement. We use the Zero Cutoff to force anything below a certain flow rate to be forced to zero, providing stable measurements at the low flow end.

Category 4: Critical Factory settings that should be changed only by Qualified Service personnel

Acceleration Limit	Defines the acceptable amount of velocity change from sequential flow measurements. Any change in flow in excess of this value should be considered a signal processing error. This determines if a Dangerous Detected state should be triggered. The Factory setting should be changed only by a Qualified Service representative.
Amplitude Discriminator max limit	Defines the upper range of the internal amplitude discriminator measurement that defines the signal amplification level. This determines if a Dangerous Detected state should be triggered. The Factory setting should be changed only by a Qualified Service representative.
Amplitude Discriminator min limit	Defines the lower range of the internal amplitude discriminator measurement that defines the signal amplification level. This determines if a Dangerous Detected state should be triggered. The Factory setting should be changed only by a Qualified Service representative.
Correlation Peak Low Limit	Determines the minimum amplitude of the cross-correlation signal peak for an acceptable signal processing measurement. This determines if a Dangerous Detected state should be triggered. The Factory setting should be changed only by a Qualified Service representative.
Velocity High Limit - Used for Volumetric High limit calculation	Defines the upper limit for an acceptable velocity measurement. A measurement beyond this value shall be considered a signal processing error as it is not physically explainable. This determines if a Dangerous Detected state should be triggered. The Factory setting should be changed only by a Qualified Service representative.
Velocity Low Limit - Used for Volumetric low limit calculation	Defines the upper limit for an acceptable velocity measurement for flow in the reverse direction. A measurement beyond this value shall be considered a signal processing error as it is not physically explainable. This determines if a Dangerous Detected state should be triggered. The Factory setting should be changed only by a Qualified Service representative.

3.2.3 List of Safety Parameters (cont.)

Category 5: Set at Factory, but may be changed by Authorized User if application requires special settings

Ch_x Errors Allowed	Defines the number of errors that must be compiled in the previous 16 readings in order to trigger an overall error condition and trip the SIL output to the Dangerous Detected state. The Factory setting should not be changed unless there are problems with the application.
Ch_x Max Peak%	Defines the upper limit of the self-adjusting “percent of peak” value used to detect the arrival of the received ultrasonic signal. This is used in the flow rate calculation. The Factory setting should not be changed unless there are problems with the application.
Ch_x Min Peak%	Defines the lower limit of the self-adjusting “percent of peak” value used to detect the arrival of the received ultrasonic signal. This is used in the flow rate calculation. The Factory setting should not be changed unless there are problems with the application.
Ch_x Pct of Peak	Defines the starting point of the self-adjusting “percent of peak” value used to detect the arrival of the received ultrasonic signal. This is used in the flow rate calculation. The Factory setting should not be changed unless there are problems with the application.
Ch_x Reynolds Correction Selection	Determines if Reynolds correction should be applied to the flow reading for each transducer measurement channel. This is used in the flow rate calculation. The Factory setting should not be changed unless there are problems with the application.

3.2.3 List of Safety Parameters (cont.)

Category 6: Set at the Factory during Calibration and should not be modified unless the application requires special settings

Calibration Factor	Overall correction factor applied to the flow measurement. This is used in the flow rate calculation. Set at Calibration, and should not be changed.
MultiK Active	Needed only if the operator wishes to use a table of correction factors to calibrate the flow velocity reading. The operator will then have to enter a table of correction factors at various flow readings, or a table of correction factors at various Reynolds Number readings.
MultiK Pairs	Needed only for the Correction Factor table. Defines the number of table entries, from 2 to 6.
MultiK Type	Needed only for the Correction Factor table. Defines whether correction factors (k-factors) will be applied, based on velocity reading or Reynolds Number reading.
MultiK VelRey_1	Needed only for the Correction Factor table. First "x" value in the table, which will be the lowest velocity or lowest Reynolds Number to use for correction.
MultiK VelRey_1	Needed only for the Correction Factor table. First "y" value in the table, which will be the correction factor (k-factor) for the lowest velocity or lowest Reynolds Number. This k-factor will be multiplied by the velocity indicated by the corresponding x-value, or the velocity that leads to the Reynolds Number for the corresponding x-value.
MultiK VelRey_2	Needed only for the Correction Factor table. Second "x" value in the table, which will be the next higher velocity or next higher Reynolds Number to use for correction.
MultiK VelRey_2	Needed only for the Correction Factor table. Second "y" value in the table, which will be the correction factor (k-factor) for the corresponding x-value, or the velocity that leads to the Reynolds Number for the corresponding x-value.
MultiK VelRey_3	Needed only for the Correction Factor table. Third "x" value in the table, which will be the next higher velocity or next higher Reynolds Number to use for correction.
MultiK VelRey_3	Needed only for the Correction Factor table. Third "y" value in the table, which will be the correction factor (k-factor) for the corresponding x-value, or the velocity that leads to the Reynolds Number for the corresponding x-value.
MultiK VelRey_4	Needed only for the Correction Factor table. Fourth "x" value in the table, which will be the next higher velocity or next higher Reynolds Number to use for correction.
MultiK VelRey_4	Needed only for the Correction Factor table. Fourth "y" value in the table, which will be the correction factor (k-factor) for the corresponding x-value, or the velocity that leads to the Reynolds Number for the corresponding x-value.
MultiK VelRey_5	Needed only for the Correction Factor table. Fifth "x" value in the table, which will be the next higher velocity or next higher Reynolds Number to use for correction.
MultiK VelRey_5	Needed only for the Correction Factor table. Fifth "y" value in the table, which will be the correction factor (k-factor) for the corresponding x-value, or the velocity that leads to the Reynolds Number for the corresponding x-value.
MultiK VelRey_6	Needed only for the Correction Factor table. Last "x" value in the table, which will be the next higher velocity or next higher Reynolds Number to use for correction.
MultiK VelRey_6	Needed only for the Correction Factor table. Last "y" value in the table, which will be the correction factor (k-factor) for the corresponding x-value, or the velocity that leads to the Reynolds Number for the corresponding x-value.

3.2.3 List of Safety Parameters (cont.)

Category 7 – Wetted Transducers: Critical Factory settings that should not be changed

Ch_x Axial Length L	Defines the axial length of each transducer path. Used in the flow rate calculation.
Ch_x Chord Wt factor	Required if the Composite Path Configuration is more than one path. Defines the weighting factor when calculating the overall volumetric flow rate from the flow rate of each transducer path. This is used in the flow rate calculation.
Ch_x Path Length P	Defines the path length of each transducer path. Used in the flow rate calculation.
Ch_x Time Buffer Offset	Determines the delay time in the transducer buffer. This is used in the flow rate calculation. The Factory setting should not be changed unless there are problems with the application.
Active TW	Determines whether or not to automatically adjust Tw value for the transducer as the measurement environment changes. Tw is the time in the wedge, or the time delay in the transducer buffer. For fluids that undergo extreme temperature changes, the Tw value may need to be recalculated as the buffer itself changes length and sound speed in response to heating and cooling. This is used in the flow rate calculation. The Factory setting should not be changed unless there are application problems.
Path Configuration	Defines the number of transducer pairs mounted on the flow cell and the arrangement of those paths. This information is critical to determining the flow measurement algorithm, as it defines how to combine the individual path measurements to create an overall flow rate.
Pipe Inner Diameter	Defines the cross-sectional area of the fluid. Used for calculating volumetric flow rate from flow velocity profile.
Pipe Outer Diameter	Required only if the Pipe Inner Diameter is not set directly. In this case the Pipe Inner Diameter will be calculated from the Pipe Outer Diameter and Pipe Wall Thickness.
Pipe Wall Thickness	Required only if the Pipe Inner Diameter is not set directly. In this case the Pipe Inner Diameter will be calculated from the Pipe Outer Diameter and Pipe Wall Thickness.
Reynolds Correction	Used on some paths, depending on Path Configuration, to correct the average flow velocity reading. Uses the fluid Reynolds number and the average flow velocity to determine the flow profile, then uses this to correct for a cross-sectional flow velocity.
Ch_x Delta T Offset	Defines a correction factor applied to the delta-t calculation. This is used in the flow rate calculation. May be used for testing or troubleshooting, to simulate a flow rate when there is no flow, but must be set back to the appropriate correction for zero flow for actual flow measurement. Critical to be sure this produces a zero flow reading at zero flow. The Factory setting should be changed only by a Qualified Service representative.

Category 7 – Clamp-On Transducers: Critical Factory settings that should not be changed

Reynolds Correction	Used on some paths, depending on Path Configuration, to correct the average flow velocity reading. Uses the fluid Reynolds number and the average flow velocity to determine the flow profile, then uses this to correct for a cross-sectional flow velocity.
Ch_x Delta T Offset	Defines a correction factor applied to the delta-t calculation. This is used in the flow rate calculation. May be used for testing or troubleshooting, to simulate a flow rate when there is no flow, but must be set back to the appropriate correction for zero flow for actual flow measurement. Critical to be sure this produces a zero flow reading at zero flow. The Factory setting should be changed only by a Qualified Service representative.

Note: Many of these parameters require Service access, so a Panametrics Service Engineer will have to do the commissioning.

3.2.4 Optional Functional Safety Parameters

There are four flow limits related to functional safety that the Operator may choose to set:

- Lower Functional Limit (LFL)
- Lower Warning Limit (LWL)
- Upper Warning Limit (UWL)
- Upper Functional Limit (UFL).

These allow an Operator to set a Lower and Upper functional safety flow range beyond which the SIS is not safe. In addition, the Operator may set warning levels to indicate that the flow rate is approaching one of the functional safety flow limits.

If used, the settings would typically follow the pattern: $LDL < LFL < LWL < UWL < UFL < UDL$. The Category 8 table below includes a detailed explanation of these parameters.

Category 8: Optional Functional Safety Settings

LFL = Lower Functional Limit	A customer may choose to set this flow rate threshold to indicate a flow rate that is either too low in the forward direction or too high in the reverse direction to be safe for the SIS. If the measured flow rate were to drop below the LFL, the SIL output would go to the level selected for the Dangerous Detected state (either Fire Low or Fire High). By default, the LFL is set to the lower design limit (LDL) of the flowmeter system.
UFL = Upper Functional Limit	A customer may choose to set this flow rate threshold to indicate a flow rate that is too high in the forward direction to be safe for the SIS. If the measured flow rate were to exceed the UFL, the SIL output would go to the level selected for the Dangerous Detected state (either Fire Low or Fire High). By default, the UFL is set to the upper design limit (UDL) of the flowmeter system.
LWL = Lower Warning Limit	If a customer uses the LFL feature, he may also choose to receive a warning before the flow rate approaches the lower functional limit. Therefore, the customer would set a LWL value, somewhat higher than the LFL value. If the flow rate fell below the LWL level, the Genesis flowmeter provides a warning message on the LCD (also retrievable by PanaView Plus software, HART, or a Modbus connection). However, if the measured flow rate is between the LWL and the LFL, the SIL output continues to measure flow. This may allow an operator to react to the decreasing flow rate value before it reaches the lower functional limit.
UWL = Upper Warning Limit	Analogous to the LWL, this is used to warn the operator that the flow rate is increasing toward the Upper Functional Limit.
LDL = Lower Design Limit	By design, our flow calculations are guaranteed to this lower limit. For the XMT1000-SIL, the minimum flow rate Panametrics designed to is -40 feet/sec (-12.5 m/sec).
UDL = Upper Design Limit	By design, our flow calculations are guaranteed to this upper limit. For the XMT1000-SIL, the maximum flow rate Panametrics designed to is 40 feet/sec (12.5 m/sec).

3.2.5 Validation of Parameter Set

The user shall be required to run a validation of the sub-system after a change of safety parameters.

3.3 Proof Tests

The objective of proof testing is to detect failures within the flowmeter that are not detected by the routine diagnostics of the instrument. The main concern is undetected failures that could prevent the Safe Output from performing its intended function.

The frequency of proof testing or the proof test interval shall be one year or less to maintain the required safety integrity of the Safe Output.

The person(s) performing the proof test of the Flowmeter should be trained in SIS operations, including bypass procedures, flowmeter maintenance and company Management of Change procedures. Tests can be executed via the LCD/keypad or PanaView Plus software. Tests can also be executed via HART, except as noted below. Refer to the *User's Manual* for information on connecting HART or PanaView Plus software to the flowmeter.

The results of the proof test shall be documented and this documentation shall be part of a plant safety management system. Any failures that are detected and that compromise functional safety should be reported to the Product Safety Officer within Panametrics. *Table 4* below describes the proof test options.

Table 4: Proof Test Options

Proof Test #1	Loop output min-to max test
	Check Configuration
Proof Test #2	Loop output min-to-max test
	Check Configuration
	SIL Output Switch test
	Verification of on-board temperature measurement
	Watchdog Test
Proof Test #3	All above tests, plus:
	Calibration against primary standard

Note: Except as noted in the tables on the following pages, the Operator must log in at the SIL User access level to execute these tests.

3.3.1 Proof Test #1

The following proof test is recommended for all flowmeters:

Step	Action
1	Electrically bypass the safety PLC by using a maintenance override function or take other appropriate action to avoid a false trip, following Management of Change procedures.
2	Set the SIL Output to go to the Fault Level specified for Force High (>21 mA), and verify that the mA current reaches that value. • Using PanaView Plus: CAL-TRIM-TEST>SIL Output Percent $> 106\%$ • Using HART: Device Setup $>$ HART Service:Operator $>$ SIL Testing $>$ SIL Output Min Max $>$ Fire High • Using LCD/Keypad: SIL Testing $>$ SIL Output Min Max $>$ Fire High This tests for compliance voltage problems such as a low loop power supply voltage or increased wiring resistance. This also tests for other possible failures.
3	Set the SIL Output to go to the Fault Level specified for Force Low, (<3.6 mA) and verify that the mA current reaches that value. • Using PanaView Plus: CAL-TRIM-TEST>SIL Output> Percent $> -2.5\%$ • Using HART: Device Setup $>$ HART Service:Operator $>$ SIL Testing $>$ SIL Output Min Max $>$ Fire Low • Using LCD/Keypad: SIL Testing $>$ SIL Output Min Max $>$ Fire Low This tests for possible failures related to quiescent current.
4	Verify all safety-critical configuration parameters. See List of Safety Parameters beginning on <i>page 13</i> .
5	Restore the loop to full operation.
6	Ensure that no alarms or warnings are present in the transmitter. • Using PanaView Plus: check the Error Window for messages. • Using HART: PV Loop Current (Verify current is in the range of 4.00 mA to 20.00 mA) • Using LCD/Keypad: watch for error messages after returning to Measure mode
7	Remove the bypass from the safety PLC or otherwise restore normal operation.

3.3.2 Proof Test #2

Proof Test #2 incorporates all the steps of Proof Test 1, plus it includes additional tests.

Step	Action
1	Electrically bypass the safety PLC by using a maintenance override function or take other appropriate action to avoid a false trip, following Management of Change procedures.
2	Set the SIL Output to go to the Fault Level specified for Force High (>21.0 mA), and verify that the mA current reaches that value. - Using PanaView Plus: CAL-TRIM-TEST>SIL Output> Percent > 106% - Using HART: Device Setup > HART Service: Operator > SIL Testing > SIL Output Min Max > Fire High - Using LCD/Keypad: SIL Testing > SIL Output Min Max > Fire High This tests for compliance voltage problems such as a low loop power supply voltage or increased wiring resistance. This also tests for other possible failures.
3	Set the SIL Output to go to the Fault Level specified for Force Low, (<3.6 mA) and verify that the mA current reaches that value. - Using PanaView Plus: CAL-TRIM-TEST>SIL Output> Percent > -2.5% - Using HART: Device Setup > HART Service:Operator> SIL Testing > SIL Output Min Max > Fire Low - Using LCD/Keypad: SIL Testing > SIL Output Min Max > Fire Low This tests for possible failures related to quiescent current.
4	Test the SIL Output Switch to verify the circuit can force the SIL Output off in case of a hardware failure. Test the SIL Output mA value with an ammeter or DCS. Record the default value. - Using PanaView Plus: CAL-TRIM-TEST>Test on Demand> Switch Test > OPEN / CLOSE - Using HART: This test cannot be conducted through HART. - Using LCD/Keypad: SIL Testing > SIL Output Analog Switch > Open Switch, Close Switch Verify that the SIL Output goes to 3.2 mA or less during "Open Switch" state. "Close Switch" should bring the SIL Output back on line, to the default value.
5	Read the temperature value from the on-board sensor, compare it to ambient temperature, and verify that this is a reasonable reading. The sensor reading should be 10-15 degrees C above ambient and less than 70°C. - MONITOR > Current Operating Temperature (Note: SIL User level not required) - Using HART: Device Setup > HART Service:Operator > SIL Testing > Board Temperature - Using LCD/Keypad: SIL Testing > On Board Temperature
Note: This table is continued on the next page.	

Step	Action
Note: This table is continued from the previous page.	
6	Execute the Watchdog Test to reboot the Flowmeter. Note: The Watchdog Test will reset the Flowmeter and lose any changed Parameters. • Using PanaView Plus: CAL-TRIM-TEST>Test on Demand> Watchdog Test > WATCHDOG TEST • Using HART: This test cannot be conducted through HART. • Using LCD/Keypad: SIL Testing > Watchdog Test Wait approximately 40 seconds for flowmeter to return to normal operation. If the test fails, the LCD and the Error Log in PanaView Plus will show an error message.
7	Verify all safety-critical configuration parameters. See List of Safety Parameters beginning on page 13.
8	Restore the loop to full operation.
9	Ensure that no alarms or warnings are present in the transmitter. • Using PanaView Plus: check the Error Window for messages. • Using HART: PV Loop Current (Verify current is in the range of 4.00 mA to 20.00 mA) • Using LCD/Keypad: watch for error messages after returning to Measure mode
10	Remove the bypass from the safety PLC or otherwise restore normal operation.

3.3.3 Proof Test #3

Proof Test #3 involves all the steps of Proof Test #2, followed by a flowmeter calibration against a reference.

Note: This process requires Service Access Level. It must be performed by a Panametrics Service Professional or a qualified customer.

3.4 Hazard and Risk Analysis to be Performed by the Customer

The impact of commissioning on adjacent operating units and facilities or other field services shall be evaluated prior to completion of commissioning. Customer safety procedures shall dictate the method for this evaluation.

[no content intended for this page]

Chapter 4. Maintenance Phase

Once the flowmeter has been properly installed and commissioned, it is ready to provide flow measurements to the SIS. From this point until Decommissioning, the flowmeter shall be in the maintenance phase of its life cycle.

4.1 User Restrictions

The Dangerous Detected state is set due to flow measurement errors or system faults. Flow measurement errors can be caused by temporary distortions in the signal traveling through flowing fluid. If a Dangerous Detected State occurs due to flow errors, the flowmeter will put the SIL Output in the DD state. The instrument will recover from a flow error without user intervention, when the flow conditions recover. Also, a Dangerous Detected State occurs due to system faults. In this case the flowmeter will put the SIL Output in DD state and it will remain that way until an Authorized User intervenes. The DD state can be cleared by executing a reset of the flowmeter. There are two methods for clearing the DD state:

- Enter the Program menu at SIL user access level. Then exit without making any changes. The flowmeter will execute a soft reset.
- or
- Turn the power off, wait 1 minute, and then turn the power back on.

Only Authorized Personnel shall be allowed to execute a reset, per the local Safety Plan at the customer site (see “Appendix A” on page 29 for details).

4.2 Repair and Replacement

There are no user-replaceable components on printed circuit assemblies, and all other spare components for the flowmeter must be purchased from Panametrics. Any failures that are detected and that compromise functional safety should be reported to the Product Safety Officer within Panametrics. When replacing the transducers or the flowmeter, follow Panametrics procedures. The user is responsible for maintaining adequate risk reduction for the Safety Instrumented Function during repair and replacement.

Repair and replacement activities must be performed by trained Service personnel, or by Authorized Customers who have Service training. This ensures functional safety compliance and keeps the Panametrics traceability database up to date.

4.3 Modifications and Traceability

4.3.1 Purpose

The modification process involves changes to hardware or software for installed systems.

Any modification at the system shall be documented by the Authorized User with the consequences of the modification to the system.

4.3.2 Traceable Components

Hardware Modifications must be performed by trained service personnel, or by authorized customers who have service training. Any hardware or firmware change to an installed system must be reflected in the traceability database at Panametrics. That is, if hardware is changed, the serial number and version of the new hardware component must be noted in the database. If firmware is changed, the new firmware version must be noted in the database. It is vital to keep the database up to date in the event that a repair or replacement action comes up as noted in “User Restrictions” on page 25.

Please contact one of the *Customer Support Centers* listed on the back cover to send updates to the traceability database.

4.4 Firmware Update

In case firmware updates are required, they shall be performed at the factory or by a Panametrics certified service technician. The user will not be required to perform any firmware updates without supervision of Panametrics personnel.

[no content intended for this page]

Chapter 5. Decommissioning Phase

Upon completion of service, the flowmeter shall be decommissioned (removed from service) by an authorized user.

5.1 Objectives

Before decommissioning any safety system from active service, be sure a proper review is conducted and obtain any required authorization. Also, maintain appropriate safety functions during decommissioning activities.

Management of change procedures shall be implemented for all decommissioning activities.

5.2 Hazard and Risk Analysis to be Performed by the Customer

The impact of decommissioning on adjacent operating units and facilities or other field services shall be evaluated prior to decommissioning.

5.3 Disposal

Disposal shall comply with the *Waste Electrical and Electronic Equipment Directive* (WEEE Directive) at the following link: http://ec.europa.eu/environment/waste/weee/index_en.htm.

Please contact one of the *Customer Support Centers* listed on the back cover to report a decommissioned product.

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Appendix A. Functional Safety Health Codes

The health codes and flow error strings in this appendix are defined by the XMT1000-SIL. The operator can access these codes via Modbus commands.

In some error modes, the SIL output will go to a DD state, indicating a non-specific problem. To determine the type of problem, send a Modbus command requesting the health register for health codes or the error register for flow error strings via PanaView Plus PC software. The health code (see *Table 5* below) or the flow error string (see *Table 6* on page 30) provides some details about the problem.

A.1 Health Code Conditions Table

Use this table to find the suggested actions to be taken for each health code error condition.

Table 5: Health Code Conditions

Error Code	HEX Value	Indication	Fault Level	Action
S0	0x00000000	NO Error	* Indication *	No action required
S1	0x00000001	In Configuration Mode	* Indication *	No action required
S2	0x00000002	Invalid User	* Warning *	Enter correct password
S3	0x00000004	Invalid request	* Warning *	Request a valid parameter
S4	0x00000008	Invalid Parameter Range	* Warning *	Use a valid value for the parameter
S5	0x00000010	Unsupported Parameter	* Warning *	Set a valid parameter
S6	0x00000020	Flow Measurement	* Error *	Check parameter settings, transducers
S7	0x00000040	Persistent Parameter CRC Fault	* Fault *	Reset to Commissioned Data Set
S8	0x00000080	Multiplexer Switch test Fault	* Fault *	Reset Flowmeter, contact Service
S9	0x00000100	ADC Bit test Fault	* Fault *	Reset Flowmeter, contact Service
S10	0x00000200	VGA test Fault	* Fault *	Check transducers, contact Service
S11	0x00000400	Clock Frequency Fault	* Fault *	Reset Flowmeter, contact Service
S12	0x00000800	CPU test Fault	* Fault *	Reset Flowmeter, contact Service
S13	0x00001000	Invariable Flash memory Fault	* Fault *	Reset Flowmeter, contact Service
S14	0x00002000	Invariable SRAM memory Fault	* Fault *	Reset Flowmeter, contact Service
S15	0x00004000	Variable Memory Fault	* Fault *	Reset Flowmeter, contact Service
S16	0x00008000	FPGA Configuration CRC fault	* Fault *	Reset Flowmeter, contact Service
S17	0x00010000	Temperature Test Fault	* Fault *	Reduce ambient temperature
S18	0x00020000	Driver Failure	* Fault *	Reset Flowmeter, contact Service
S19	0x00040000	Watch Dog failure	* Fault *	Reset Flowmeter, contact Service
S20	0x00080000	Analog Out Read back failure	* Fault *	Reset Flowmeter, contact Service
S21	0x00100000	Stack Overflow failure	* Fault *	Reset Flowmeter, contact Service
S22	0x00200000	Sequence or Windowed Watch Dog failure	* Fault *	Reset Flowmeter, contact Service
S23	0x00400000	Initialization failed	* Fault *	Review parameters
S24	0x00800000	DSP Hardware Errors	* Fault *	Reset Flowmeter, contact Service

Table 5: Health Code Conditions(Continued)

Error Code	HEX Value	Indication	Fault Level	Action
S25	0x01000000	DSP Exception	* Fault *	Reset Flowmeter, contact Service
S26	0x02000000	Default ISR (DSP Exception)	* Fault *	Reset Flowmeter, contact Service
S27	0x04000000	DSP Reset ISR (DSP Exception)	* Fault *	Reset Flowmeter, contact Service
S28	0x08000000	Software fault	* Fault *	Reset Flowmeter, contact Service
S29	0x10000000	SIL Output Loop Open	* Fault *	Investigate SIL output wiring, execute SIL Output Analog Switch to verify the switch is working correctly, contact Service

A.2 Flow Error Strings Table

Use this table to find the suggested actions to be taken for each flow measurement error condition.

Table 6: Flow Error Strings

Error Code	Hex Value	Indication	Fault Level	Action
E1	0x00000200	SNR	*Error*	No action required
E2	0x00000100	SoundSpeed	*Error*	No action required
E3	0x00000080	VelocityRange	*Error*	No action required
E4	0x00000040	SignalQuality	*Error*	No action required
E5	0x00000020	Amplitude	*Error*	No action required
E6	0x00000010	CycleSkip	*Error*	No action required
E15	0x00000008	ActiveTW	*Error*	No action required
E22	0x00000002	SingleChAccuracy	*Error*	No action required
E23	0x00000004	MultiChAccuracy	*Error*	No action required
E28	0x10000000	SIL	*Error*	No action required
E29	0x00000001	VelocityWarning	*Warning*	No action required
E31	0x40000000	Not Calibrated	*Error*	Calibrate the flowmeter

Appendix B. XMT1000 SILGlossary

Access Levels: There are four access levels in the flowmeter: Operator, Admin, Factory and Upgrade. Each Data Set has parameters that include all four Access Levels.

Authorized User: An operator of a SIL Instrument that has been properly trained in Functional Safety and is therefore authorized to operate and maintain the SIL instrument. Access that is restricted to Authorized Users only may be controlled by password protection or other security means.

Data Set: A set of programmable parameters in the flowmeter that control the Safety Function. The flowmeter has three complete data sets. There is a Factory Set, a Commissioned Set, and an Active Set. Each Data Set contains an identical set of parameters, but with different programmed values. Each Data Set contains some parameters that are only accessible with a Factory Password, some that are accessible with a Admin Password, some that are accessible with a SIL User password, and some that are accessible with a General User password.

Health Codes: The flowmeter can provide several Health Codes that indicate the nature of an internal error or warning condition. These are accessible via the PanaView Plus PC Software. *Appendix A* lists these codes in *Table 5* on page 29.

Life Cycle: A Functional Safety product has three basic Life Cycle stages: Commissioning, Maintenance, and Decommissioning. Each stage has Functional Safety concerns and actions that are described in this manual.

Proof Testing: The flowmeter has many self-tests that it performs continuously to ensure the integrity of the Safe Output value. But there are some functions that can not be tested routinely because they would cause an alarm condition, instrument reset, etc. These functions must be tested periodically through a process called Proof Testing. This consists of taking the flowmeter offline by disconnecting it from the SIS or otherwise preventing the SIS from using its SIL Output in safety calculations. The Authorized User then performs certain tests and records the results per the Customer Safety Plan (outside the scope of this manual). Finally, the Authorized User brings the flowmeter back on line by reconnecting it with the SIS.

SIL Output: Only the SIL Analog Output is SIL rated and may be used as an input to the SIS.

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